THE SMALLEST POSSIBLE INTERACTION RADIUS FOR FLOCK SYNCHRONIZATION*

GE CHEN^{\dagger}, ZHIXIN LIU^{\dagger}, AND LEI GUO^{\dagger}

Abstract. This paper investigates the synchronization behavior of a class of flocks modeled by the nearest neighbor rules. While connectivity of the associated dynamical neighbor graphs is crucial for synchronization, it is well known that the verification of such dynamical connectivity is the core of theoretical analysis. Ideally, conditions used for synchronization should be imposed on the model parameters and the initial states of the agents. One crucial model parameter is the interaction radius, and we are interested in the following natural but complicated question: What is the smallest interaction radius for synchronization of flocks? In this paper, we reveal that, in a certain sense, the smallest possible interaction radius approximately equals $\sqrt{\log n/(\pi n)}$, with n being the population size, which coincides with the critical radius for connectivity of random geometric graphs given by Gupta and Kumar [Critical power for asymptotic connectivity in wireless networks, in Stochastic Analysis, Control, Optimization and Applications, Birkhäuser Boston, Boston, MA, 1999, pp. 547– 566].

Key words. multiagent system, Vicsek's model, synchronization, random geometric graph, spectral gap, percolation theory

AMS subject classifications. 92D50, 93C55, 60K35

DOI. 10.1137/100812719

1. Introduction. Recent motivations in the study of complex systems have led to great interest in the collective behavior of flocks or multiagent systems; see [1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12] among many others. A central issue in the investigation of multiagent systems is to understand how local interactions among the agents lead to global behavior of the whole group.

In this paper, we focus our attention on a group of flocks, or mobile agents, modeled by the nearest neighbor rules and based on the well-known multiagent model proposed by Vicsek et al. in [3]. The model consists of n autonomous agents moving in the plane with the same speed $v_n(v_n > 0)$ but with different headings. Each agent's heading is updated according to a local rule based on the average direction of its neighbors. Two agents are called neighbors if and only if the distance between them is less than a predefined radius $r_n(r_n > 0)$. Let us assume that the n agents are labeled by $1, 2, \ldots, n$. Two agents i and j are neighbors at time t if and only if $||X_i(t) - X_j(t)||_2 \leq r_n$, where $|| \cdot ||_2$ denotes the Euclidean norm. For any agent $i(1 \leq i \leq n)$, the set of its neighbors at time $t(t = 0, 1, \ldots)$ is denoted by $\mathcal{N}_i(t)$. By the definition of neighbors, we see that each agent is a neighbor of itself, i.e., $i \in \mathcal{N}_i(t)$, for all $t \geq 0$ and $1 \leq i \leq n$. The position and heading of the agent i at time t are denoted by $X_i(t)(\in \mathbb{R}^2)$ and $\theta_i(t)(\in (-\pi, \pi])$, respectively, which are updated by

(1.1)
$$X_i(t+1) = X_i(t) + v_n(\cos\theta_i(t+1), \sin\theta_i(t+1)),$$

^{*}Received by the editors October 25, 2010; accepted for publication (in revised form) May 1, 2012; published electronically July 24, 2012. This work was supported by the National Natural Science Foundation of China under grants 60821091 and 60804043.

http://www.siam.org/journals/sicon/50-4/81271.html

[†]Key Laboratory of Systems and Control, Academy of Mathematics and Systems Science, Chinese Academy of Sciences, Beijing 100190, China (chenge@amss.ac.cn, Lzx@amss.ac.cn, Lguo@amss.ac.cn).

(1.2)
$$\theta_i(t+1) = \arctan \frac{\sum_{j \in \mathcal{N}_i(t)} \sin \theta_j(t)}{\sum_{j \in \mathcal{N}_i(t)} \cos \theta_j(t)} + \delta_i(t),$$

where $\delta_i(t)$ denotes a random noise [3].

As pointed out by Vicsek et al. [3], such a model can be used to study the gathering and phase transition of nonequilibrium systems and may be applied to investigate the clustering and migration in some biological systems. By computer simulations, the authors of [3] revealed that if the population density is large and the noise is small, all agents tend to eventually move in the same direction. Due to its simplicity and fundamental importance in the investigation of multiagent systems, this model has attracted much attention in biology, physics, computer science, control theory, and mathematics. However, the theoretical analysis of system (1.1)-(1.2) is difficult because of the nonlinearity and randomness of (1.2). An important step forward in analyzing the above model is given by Jadbabaie, Lin, and Morse in [6], where they omitted the noise effect and linearized the heading updating rule (1.2) as follows:

(1.3)
$$\theta_i(t+1) = \frac{1}{|\mathcal{N}_i(t)|} \sum_{j \in \mathcal{N}_i(t)} \theta_j(t),$$

where $|\cdot|$ denotes the cardinality of the corresponding set. They proved that if the associated dynamical neighbor graphs are contiguously jointly connected, the above model will reach synchronization in the sense that there exists a common $\bar{\theta}$ such that for all $i(1 \le i \le n)$,

(1.4)
$$\lim_{t \to \infty} \theta_i(t) = \bar{\theta}.$$

After that, Savkin in [7] investigated the model with discrete headings and showed that if the limit of the neighbor graphs is connected, then synchronization can also be achieved. In [9], Ren and Beard studied the case where the neighbor graphs are directed and showed that synchronization can be achieved if the union of the interaction graphs has a spanning tree frequently enough.

In fact, most existing studies resort to certain connectivity conditions on the dynamical neighbor graphs, and these conditions are hard to verify. Therefore the corresponding analysis is not theoretically complete. One notable exception in the study of flocks is the interesting paper by Cucker and Smale [4], where global interactions are considered with weights of interactions decaying with the distances among agents. However, an unresolved central issue is how to guarantee the connectivity of the dynamical neighbor graphs resulting from local interactions using conditions imposed on only the initial states, the moving speed v_n , and the interaction radius r_n .

To give a complete analysis for the synchronization behavior of the system, Tang and Guo [8] introduced a random framework, assuming that the initial positions and headings of all agents are uniformly and independently distributed, as those in [3]. They show that for any given positive model parameters, the flocking model based on (1.1) and (1.3) will synchronize with large probability, giving the first complete theoretical result in this direction. Furthermore, in [12] they proved that if $\sqrt[6]{\log n/n} = o(r_n)$ and $v_n = O(r_n^5/\log n)$, then the model will synchronize.^{1,2} Based

Downloaded 08/05/12 to 159.226.47.124. Redistribution subject to SIAM license or copyright; see http://www.siam.org/journals/ojsa.php

¹For two positive sequences $\{a_n, n \geq 1\}$ and $\{b_n, n \geq 1\}$, $a_n = o(b_n)$ means that

 $[\]lim_{n\to\infty} (a_n/b_n) = 0.$ ²For two positive sequences $\{a_n, n \ge 1\}$ and $\{b_n, n \ge 1\}$, $a_n = O(b_n)$ means that there exists a positive constant c independent of n such that $a_n \leq cb_n$ for large enough n.

on their results, Liu and Guo [10] investigated the system (1.1)–(1.2) without noise and provided a similar condition for synchronization. However, the theoretical analysis of the (linearized) Vicsek's model with the radius $r_n = O(\sqrt[6]{\log n/n})$ is still lacking, and the question concerning the smallest possible radius for synchronization is never investigated in this context.

We will carry out our analysis under the assumption that all agents are independently and uniformly distributed in $[0,1]^2$ with arbitrary headings in $(-\pi,\pi]$ at the initial time. As pointed out by Jadbabaie, Lin, and Morse in [6], the connectivity of the neighbor graphs is important for synchronization. Gupta and Kumar in [13] proved that the initial neighbor graph with radius $\sqrt{(c_n + \log n)/\pi n}$ is connected with high probability (w.h.p.)³ if and only if $c(n) \to \infty$. We refer to $\sqrt{(c_n + \log n)/\pi n}$ with $c(n) \to \infty$ as supercritical radius for connectivity. In this paper, we will show that if the interaction radius is taken as the supercritical radius, then the system can reach synchronization w.h.p. under some restriction on the speed: otherwise, if the radius satisfies (2.4) given in the next section, then the system may not synchronize w.h.p. for any nonnegative speed. From the analysis in [8], the spectral gap of the initial neighbor graph plays an important role for the synchronization rate of the model. But the methods used in [8] are not suitable for the case of $r_n = O(\sqrt{\log n/n})$ since the radius is too small to meet the prerequisite of the method. In this paper, we will provide a novel approach to estimate the spectral gap of the random geometric graph with radius $O(\sqrt{\log n/n})$. Furthermore, by analyzing the system dynamics, we will prove the synchronization condition of the flocks, without resorting to any assumption on the dynamical behavior of the flocks themselves.

The rest of the paper is organized as follows. In section 2, we will present the main results of this paper. The proof of the main results is given in section 3. More detailed analysis of the auxiliary results will be given in section 4. A simulation example is put in section 5. Section 6 concludes the paper with remarks.

2. Main results. The objective of this paper is to study the synchronization behavior of the dynamical system (1.1) and (1.3). From the description of the model, we know that the initial states of all agents and the model parameters will determine the trajectories of all agents. Throughout this paper, we assume that the initial positions of all agents are independently and uniformly distributed in $[0, 1]^2$ with arbitrary initial headings in $(-\pi, \pi]$. All analysis proceeds under the above assumption without further explanations.

Similar to [10], we will use a graph sequence $\{G(t), t = 0, 1, ...\}$ to describe the relationship among neighbors. For $t \ge 0$, define

$$G(t) = G(\{X_1(t), \dots, X_n(t)\}, E(t))$$

to be the position graph of the model at time t, where $E(t) = \{(i, j) : ||X_i(t) - X_j(t)|| \le r_n\}$. Obviously, the graphs formed in this way are undirected, and for all $1 \le i \le n$ and $t \ge 0$, $(i, i) \in E(t)$. Denote by P(t) the average matrix of the graph G(t), i.e.,

$$\forall i, j = 1, 2, \dots, n, \quad (P(t))_{ij} = \begin{cases} \frac{1}{|\mathcal{N}_i(t)|} & \text{if } (i, j) \in E, \\ 0 & \text{otherwise.} \end{cases}$$

1952

³We say that a sequence of events E_n occurs w.h.p. if $\lim_{n\to\infty} P[E_n] = 1$.

Let $\theta(t) := (\theta_1(t), \theta_2(t), \dots, \theta_n(t))^T$; then the iteration rule of the headings and positions of the model based on (1.1) and (1.3) can be rewritten as

(2.1)
$$\begin{cases} \theta(t+1) = P(t)\theta(t) \\ X_i(t+1) = X_i(t) + v_n(\cos\theta_i(t+1), \sin\theta_i(t+1)) \end{cases} \quad \forall t \ge 0, 1 \le i \le n. \end{cases}$$

Note that under the assumption on the initial positions, the graph G(0) is a random geometric graph, which has been studied in detail in, e.g., [15]. One of the classical result concerning the connectivity of the random geometric graph can be stated as follows.

LEMMA 2.1 (see [13]). The initial random geometric graph G(0) is connected w.h.p. if and only if r_n satisfies

(2.2)
$$\lim_{n \to \infty} \left(\pi n r_n^2 - \log n \right) = \infty.$$

Based on this lemma, Gupta and Kumar in [14] called $\sqrt{\log n/(\pi n)}$ the *critical* radius for connectivity of G(0). In this paper, we will show that in a probability sense, this critical radius can be regarded as the smallest possible radius for synchronization of the flocks. The main results of this paper are formulated as the following theorem.

THEOREM 2.2. Suppose that the *n* agents are independently and uniformly distributed in $[0,1]^2$ at the initial time t = 0. If r_n satisfies (2.2) and v_n satisfies

(2.3)
$$v_n = o\left(r_n(\log n)^{-1}n^{-2}\right),$$

then the system (2.1) will synchronize w.h.p. for arbitrary initial headings. Moreover, if r_n satisfies

(2.4)
$$\lim_{n \to \infty} \left(\pi n r_n^2 + 3 \log \log n - \log n \right) = -\infty,$$

then w.h.p. there exist some initial headings such that the system (2.1) cannot reach synchronize for any speed $v_n \ge 0$.

The proof of this theorem is in section 3.

Before closing this section, we propose a conjecture (which is intuitively correct) on the system (2.1), in terms of the values of the speed and the radius for synchronization.

CONJECTURE 2.3. Suppose n agents are distributed in a plane and the initial positions are given. If the system (2.1) can synchronize with speed v and radius r, then it will also uniformly synchronize with speed $v_1 \in (0, v)$ and radius r, or with speed v and radius $r_1 > r$.

3. Proof of Theorem 2.2. To prove Theorem 2.2, we need to estimate the maximum degree, the minimum degree, and the eigenvalues of the average matrix of the random geometric graph G(0). For this purpose, we need to introduce some notation.

Define the large deviations rate function $H: [0, \infty) \to \mathbb{R}$ by H(0) = 1 and

$$H(a) = 1 - a + a \log a, \quad a > 0.$$

Note that H(1) = 0 and that the unique turning point of H is the minimum at 1. Also, H(a)/a is increasing on $(1, \infty)$. Let $H_{-}^{-1} : [0, 1] \to [0, 1]$ be the unique inverse of the restriction of H to [0, 1], and let $H_{+}^{-1} : [0, \infty) \to [1, \infty)$ be the inverse of the restriction of H to $[1, \infty)$; see [15] for the properties of H. Denote by d_i the degree of the vertex i in G(0), i.e., the number of neighbors of the agent i at the initial time instant. Set

$$d_{\max} := \max_{1 \leq i \leq n} d_i \quad \text{ and } \quad d_{\min} := \min_{1 \leq i \leq n} d_i.$$

The estimation for the maximum and minimum degrees of the initial random geometric graph G(0) have been given by Penrose [15], as will be described by the following lemma.

LEMMA 3.1. Suppose that $\pi n r_n^2 / \log n \to w \in (1, \infty]$ and $r_n \to 0$ as $n \to \infty$. Then with probability 1,

(3.1)
$$\lim_{n \to \infty} \left(\frac{d_{\max}}{n \pi r_n^2} \right) = H_+^{-1} \left(\frac{1}{w} \right)$$

and

(3.2)
$$\lim_{n \to \infty} \left(\frac{d_{\min}}{n \pi r_n^2} \right) = \min \left(H_-^{-1} \left(\frac{1}{w} \right), \frac{1}{4} \right).$$

Proof. The assertions (3.1) and (3.2) are indicated by Theorems 6.14 and 7.14 of [15].

COROLLARY 3.2. If r_n satisfies (2.2), then $d_{\max} < 3d_{\min} \log n \ w.h.p.$

Proof. For the case where $\pi n r_n^2 \geq 3 \log n/e$, by Lemma 3.1 we see that $d_{\max} < d_{\min} \log n$ holds almost surely for large n. Next, we will discuss the case where $\pi n r_n^2 < 3 \log n/e$. Note that d_{\max} increases with r_n ; by Lemma 3.1, the following inequality holds almost surely for large n:

$$d_{\max} \le \frac{3\log n}{e} H_{+}^{-1}\left(\frac{e}{3}\right) (1+o(1)) < \frac{3\log n}{e} H_{+}^{-1}(1) = 3\log n.$$

Also, by Lemma 2.1, $d_{\min} \ge 1$ w.h.p., and thus our result yields.

Next, we will estimate the eigenvalues of G(0). Let $D = (d_{ij})_{n \times n}$ denote the degree matrix of G(0), which is a diagonal matrix with diagonal entries $d_{ii} = d_i$. Obviously, the matrix $D^{1/2}P(0)D^{-1/2}$ is symmetric, so all eigenvalues of P(0) are real numbers. On the other hand, all entries of P(0) are nonnegative, and $\sum_{j=1}^{n} (P(0))_{ij} = 1, i = 1, 2, \ldots, n$, so the average matrix P(0) is a stochastic matrix. The eigenvalues of P(0), denoted by $\lambda_i, 1 \leq i \leq n$, with λ_i being the *i*-largest eigenvalues of P(0), satisfy the inequalities

$$|\lambda_i| \le 1, \quad 1 \le i \le n$$

which means that

$$1 = \lambda_1 \ge \lambda_2 \ge \cdots \ge \lambda_n \ge -1.$$

Define the essential spectral radius $\overline{\lambda}$ of G(0) as

$$\lambda = \lambda(P(0)) := \max\{|\lambda_2|, |\lambda_n|\}.$$

We remark that for the case where $\lim_{n\to\infty} (nr_n^2/\log n) = \infty$, Tang and Guo [8] proved that the essential spectral radius of G(0) satisfies the following inequality w.h.p. for large n:

(3.3)
$$\bar{\lambda} \le 1 - \frac{\pi r_n^2}{512(r_n + \sqrt{6})^4} (1 + o(1)).$$

However, the methods used in [8] cannot be applied to estimate the spectral gap of G(0) for the case of $r_n = O(\sqrt{\log n/n})$ since the interaction radius is too small to satisfy the condition of Lemma 4 in [8], which plays a key role in the estimation of $\overline{\lambda}$. In this paper, we will use some methods from percolation theory to study the essential spectral radius of G(0) for the case where r_n satisfies (2.2).

THEOREM 3.3. Assume that $r_n \leq 1$. Then there exists a constant c > 0 such that the inequality $\bar{\lambda} \leq 1 - cr_n^2$ holds w.h.p. if and only if r_n satisfies (2.2).

The proof of Theorem 3.3 is given in section 4.

For $\eta > 0$, we write $Po(\eta)$ for any Poisson random variable with parameter η . Define a Poisson point process \mathcal{P}_{η} by $\mathcal{P}_{\eta} := \{Y_1, Y_2, \ldots, Y_{Po(\eta)}\}$, where $\{Y_1, Y_2, \ldots\}$ is the set of vertices independently and uniformly distributed in $[0, 1]^2$ and $Po(\eta)$ is independent of $\{Y_1, Y_2, \ldots\}$; see section 1.7 in [15]. For a Borel set $A \subseteq [0, 1]^2$, $|\mathcal{P}_{\eta} \cap A|$, the number of the vertices lying in A is a Poisson random variable with parameter $\eta \mathcal{L}(A)$, where $\mathcal{L}(\cdot)$ denotes the Lebesgue measure in this paper. For any Borel set $A_1, A_2 \subseteq [0, 1]^2$, if $\mathcal{L}(A_1 \cap A_2) = 0$, then the random variables $|\mathcal{P}_{\eta} \cap A_1|$ and $|\mathcal{P}_{\eta} \cap A_2|$ are mutually independent. This property is called *spatial independence* of a Poisson point process.

Proof of Theorem 2.2. We will first prove the sufficient part of Theorem 2.2.

For $r_n > 1$, under the condition (2.3), we can directly deduce that the system (2.1) can reach synchronization by Theorem 1 of [8]. Thus, we just need to consider the case where $r_n \leq 1$. By Theorem 3.3 and (2.2), we see that there exists a constant c > 0 such that

(3.4)
$$\lim_{n \to \infty} P\left(\bar{\lambda} \le 1 - cr_n^2\right) = 1.$$

Let E_n denote the event $\overline{\lambda} \leq 1 - cr_n^2$, and let \widetilde{E}_n denote the event $d_{\max} < 3d_{\min} \log n$. Define F_n to be the event

$$\bigcap_{\leq i,j \leq n} \left\{ \|X_i(0) - X_j(0)\|_2 \notin \left(r_n - o\left(\frac{1}{n^2 r_n}\right), r_n + o\left(\frac{1}{n^2 r_n}\right)\right) \right\}.$$

Using Boole's inequality, we have

1

$$\begin{split} P(F_n^c) &\leq \sum_{i \neq j} P\left(\|X_i(0) - X_j(0)\|_2 \in \left(r_n - o\left(\frac{1}{n^2 r_n}\right), r_n + o\left(\frac{1}{n^2 r_n}\right)\right) \right) \\ &< n^2 \int_{x \in [0,1]^2} P\left(\|x - X_j(0)\|_2 \in \left(r_n - o\left(\frac{1}{n^2 r_n}\right), r_n + o\left(\frac{1}{n^2 r_n}\right)\right) \right) dx \\ &< n^2 5 \pi r_n \cdot o\left(\frac{1}{n^2 r_n}\right) \to 0 \quad \text{as} \quad n \to \infty, \end{split}$$

where the property that the initial positions are independently and uniformly distributed in $[0,1]^2$ is used in the last inequality. Combining (3.5) with (3.4) and Corollary 3.2, we can deduce that

$$(3.5) P(E_n \cap E_n \cap F_n) \to 1 \quad \text{as} \ n \to \infty.$$

We assert that if the speed v_n satisfies (2.3), then for all $t \ge 0$, the topology of G(t) remains unchanged given $E_n \cap \tilde{E}_n \cap F_n$. We will prove this assertion by induction.

For t = 0, the assertion is obviously true. Assume that the assertion holds for all $s \le t$, that is, P(s) = P(0) for all $s \le t$. Thus, by (2.1), we have

$$\theta(s+1) = P^s(0)\theta(0) \quad \forall \ 0 \le s \le t.$$

Combining this with Proposition 3 in [16], for all integers $s \in [0, t]$ and $i, j \in [1, n]$ we have

$$(3.6) \qquad \left| \theta_i(s+1) - \theta_j(s+1) \right| = \left| \sum_{k=1}^n \left[(P^s(0))_{ik} - (P^s(0))_{jk} \right] \theta_k(0) \right| \\ \leq \pi \sum_{k=1}^n \left| (P^s(0))_{ik} - (P^s(0))_{jk} \right| \le \pi \sqrt{n} \left(\sqrt{\frac{d_{\max}}{d_i}} + \sqrt{\frac{d_{\max}}{d_j}} \right) \bar{\lambda}^s \\ \le 2\pi \sqrt{3n \log n} \cdot \bar{\lambda}^s,$$

where the assertion conditions E_n and \tilde{E}_n are used in the last inequality. Set

$$d_{ij}(t+1) := \|X_i(t+1) - X_j(t+1) - X_i(0) + X_j(0)\|_2.$$

Subsequently using (2.1), the triangle inequality, and standard goniometric formulae, we have

(3.7)
$$d_{ij}(t+1) = \left\| v_n \sum_{s=1}^{t+1} (\cos \theta_i(s), \sin \theta_i(s)) - v_n \sum_{s=1}^{t+1} (\cos \theta_j(s), \sin \theta_j(s)) \right\|_2$$
$$\leq v_n \sum_{s=1}^{t+1} \| (\cos \theta_i(s) - \cos \theta_j(s), \sin \theta_i(s) - \sin \theta_j(s)) \|_2$$
$$= v_n \sum_{s=1}^{t+1} \sqrt{2 - 2\cos[\theta_i(s) - \theta_j(s)]} \leq v_n \sum_{s=1}^{t+1} |\theta_i(s) - \theta_j(s)|,$$

where the inequality $\cos x \ge 1 - x^2/2$ is also used. Set $t_0 := \min\{t : 2\pi\sqrt{3n\log n} \cdot \bar{\lambda}^t \le 2\pi\}$. Then

$$t_0 = \left\lceil \frac{\log \frac{1}{\sqrt{3n \log n}}}{\log \bar{\lambda}} \right\rceil \le \frac{-\log(3n \log n)}{2 \log \bar{\lambda}} + 1,$$

where $\lceil x \rceil$ denotes the smallest integer no less than x. Hence, by (3.6) and the inequality $1 - x < -\log x$ for $x \in (0, 1)$, we have

$$\max_{i,j} \sum_{s=1}^{t+1} |\theta_i(s) - \theta_j(s)| \le 2\pi t_0 + \sum_{s=t_0+1}^{t+1} 2\pi \sqrt{3n \log n} \cdot \bar{\lambda}^s$$
$$< 2\pi \left(\frac{-\log(3n \log n)}{2 \log \bar{\lambda}} + 1 \right) + \left(\frac{2\pi \sqrt{3n \log n}}{1 - \bar{\lambda}} \right) \bar{\lambda}^{\frac{-\log(3n \log n)}{2 \log \bar{\lambda}}}$$
$$= O\left(\frac{\log n}{1 - \bar{\lambda}} \right) = O\left(r_n^{-2} \log n \right).$$

Substituting this inequality and (2.3) into (3.7), we can obtain that

(3.8)
$$\max_{i,j} d_{ij}(t+1) \le v_n \max_{i,j} \sum_{s=1}^{t+1} |\theta_i(s) - \theta_j(s)| = o\left(\frac{r_n}{n^2 \log n} \cdot \frac{\log n}{r_n^2}\right) = o\left(\frac{1}{n^2 r_n}\right),$$

Copyright © by SIAM. Unauthorized reproduction of this article is prohibited.

1956



FIG. 1. If A_k happens, then the system will not synchronize by setting the initial headings of the agents lying in $B(x_k, \varepsilon_n)$ to be $-\pi/2$ and the others to be $\pi/2$.

which means that the position between any two agents changed at time t is bounded by $o(\frac{1}{n^2r_n})$ in comparison with that at the initial time. Combining (3.8) with the condition F_n , we know that, compared with G(0), the topology of the graph G(t+1)is unchanged w.h.p.

By induction, our assertion holds for all $t \ge 0$, which means that the inequality (3.6) holds for all $t \ge 0$. Thus, the system (2.1) can reach synchronization.

It remains to prove the necessary part of the theorem. Set

$$M_n := \left\lfloor \sqrt{\pi n / (4 \log n)} \right\rfloor - 1,$$

where |x| denotes the largest integer no bigger than x. Define the point

$$x_k := \left((2k+1)\sqrt{\log n/(\pi n)}, 0 \right) \in [0,1]^2, \ k = 0, \dots, K_n.$$

Let $b_n := \log n - 3 \log \log n - \pi n r_n^2$; then by (2.4)

 $b_n < \log n - 3 \log \log n$ and $\lim_{n \to \infty} b_n = \infty$.

Take $\varepsilon_n = \sqrt{1/(\pi n \log n)}$. Let (3.9) \mathcal{X}_n :

.9)
$$\mathcal{X}_n := \{X_1(0), X_2(0), \dots, X_n(0)\}$$

denote the *n* vertices independently and uniformly distributed in $[0, 1]^2$. For any integer $k \in [0, M_n]$, define the event

$$A_{k} := \left\{ \mathcal{X}_{n} \cap B\left(x_{k}, \varepsilon_{n}\right) \neq \emptyset, \mathcal{X}_{n} \cap \left[B\left(x_{k}, r_{n} + \varepsilon_{n}\right) \setminus B\left(x_{k}, \varepsilon_{n}\right)\right] = \emptyset \right\},\$$

where $B(x,r) := \{y \in \mathbb{R}^2 : ||x-y||_2 \le r\}$ denotes the ball centered at x with radius r. If the event $A_k (k \in [0, M_n])$ happens, then the agents lying in $B(x_k, \varepsilon_n)$ do not have any neighbor at the initial time. For such a case, the system (2.1) will not synchronize by setting the initial headings of the agents lying in $B(x_k, \varepsilon_n)$ to be $-\pi/2$ and the others to be $\pi/2$; see Figure 1. Thus, to prove the necessary part we just need to verify the following equation:

(3.10)
$$\lim_{n \to \infty} P\left(\bigcup_{0 \le k \le M_n} A_k\right) = 1.$$

Set $\eta(n) := n + n^{3/4}$ and $\lambda(n) := n - n^{3/4}$. Let $\mathcal{P}_{\eta(n)}$ and $\mathcal{P}_{\lambda(n)}$ denote a Poisson point process in $[0, 1]^2$ with parameters $\eta(n)$ and $\lambda(n)$, respectively. Using Lemma 1.4 in [15], for large n we can get

$$(3.11) P\left(\mathcal{X}_n \subseteq \mathcal{P}_{\eta(n)}\right) = P\left(Po(\eta(n)) \ge n\right) > 1 - e^{-n^{1/4}}$$

(3.12) and
$$P\left(\mathcal{P}_{\lambda(n)} \subseteq \mathcal{X}_n\right) = P(Po(\lambda(n)) \le n) > 1 - e^{-n^{1/4}}.$$

Define the event

$$\widetilde{A}_{k} := \left\{ \mathcal{P}_{\lambda(n)} \cap B\left(x_{k}, \varepsilon_{n}\right) \neq \emptyset, \mathcal{P}_{\eta(n)} \cap \left[B\left(x_{k}, r_{n} + \varepsilon_{n}\right) \setminus B\left(x_{k}, \varepsilon_{n}\right)\right] = \emptyset \right\};$$

then by (3.11) and (3.12),

$$P\left(\bigcup_{0\leq k\leq M_n} A_k\right) \geq P\left(\bigcup_{0\leq k\leq M_n} \widetilde{A}_k, \mathcal{P}_{\lambda(n)} \subseteq \mathcal{X}_n, \mathcal{X}_n \subseteq \mathcal{P}_{\eta(n)}\right)$$

$$(3.13) \qquad \geq P\left(\bigcup_{0\leq k\leq M_n} \widetilde{A}_k\right) + P\left(\mathcal{P}_{\lambda(n)} \subseteq \mathcal{X}_n\right) + P\left(\mathcal{X}_n \subseteq \mathcal{P}_{\eta(n)}\right) - 2$$

$$> P\left(\bigcup_{0\leq k\leq M_n} \widetilde{A}_k\right) - 2e^{-n^{1/4}}.$$

Also, using the spatial independence of the Poisson point process and Taylor's expansion,

$$\begin{split} P\left(\bigcup_{0 \le k \le M_n} \widetilde{A}_k\right) &= 1 - P\left(\bigcap_{0 \le k \le M_n} \widetilde{A}_k^c\right) = 1 - \prod_{0 \le k \le M_n} \left[1 - P\left(\widetilde{A}_k\right)\right] \\ &= 1 - \left[1 - \left(1 - e^{-\lambda(n)\pi\varepsilon_n^2/2}\right)e^{-\eta(n)\pi(r_n^2 + 2r_n\varepsilon_n)/2}\right]^{M_n + 1} \\ &= 1 - \left[1 - \frac{1}{2\log n} \cdot n^{-\frac{1}{2}}(\log n)^{\frac{3}{2}}e^{\frac{b_n}{2}} - \sqrt{1 - b_n/\log n}(1 + o(1))\right]^{M_n + 1} \\ &= 1 - \exp\left(-\frac{1}{2}(M_n + 1)n^{-\frac{1}{2}}(\log n)^{\frac{1}{2}}e^{\frac{b_n}{2}} - \sqrt{1 - \frac{b_n}{\log n}}\right)(1 + o(1)) \\ &\to 1 \quad \text{as} \quad n \to \infty. \end{split}$$

Combining this with (3.13) yields (3.10).

Remark 3.4. From the proof of Theorem 2.2, we see that the speed v_n is so small that the topology of the neighbor graph remains unchanged during the evolution of the system. However, the relaxation of the restriction on the speed is very hard, since the estimation of the essential spectral radius of $P(t)P(t-1)\cdots P(0)$ is still open in the inhomogeneous Markov chain theory even if only one edge is changed in the neighbor graph; see Problem 1.1 in [17]. The restriction on the speed may be relaxed if the above open problem is resolved.

4. Proof of Theorem 3.3. First, we will provide the proof of the sufficient part of Theorem 3.3. For the case where $\pi n r_n^2 \ge (\log n)^2$, the inequality $\bar{\lambda} \le 1 - cr_n^2$ holds w.h.p. by Theorem 3 in [8]. Therefore, we just need to consider the case where

(4.1)
$$\pi n r_n^2 \le (\log n)^2$$
 and $\lim_{n \to \infty} (\pi n r_n^2 - \log n) = \infty.$

In this section we use $G(\mathcal{X}_n; r_n)$ to denote the initial random geometric graph G(0). Divide the unit square $[0, 1]^2$ into K_n^2 small squares with the length of each side equal to $1/K_n$, where $K_n := \lceil \sqrt{5}/r_n \rceil$. Denote these small squares by $S_1, S_2, \ldots, S_{K_n^2}$. Set

$$\alpha_n := E\left[|\mathcal{X}_n \cap S_1|\right] = \frac{n}{\left\lceil \frac{\sqrt{5}}{r_n} \right\rceil^2},$$

where \mathcal{X}_n is defined by (3.9). Define

$$\Delta_n := \max_{1 \le i \le K_n^2} |\mathcal{X}_n \cap S_i|.$$

We will consider the upper bound of Δ_n first.

LEMMA 4.1. Assume that r_n satisfies (4.1). Then, with probability 1, $\Delta_n < 21\alpha_n$ for large enough n.

Proof. Since the initial positions $X_j(0), j = 1, 2, ..., n$, are independently and uniformly distributed in $[0,1]^2$, $P(X_j(0) \in S_i) = 1/K_n^2, 1 \le j \le n, i \in [1, K_n^2]$, and $|\mathcal{X}_n \cap S_i|$ is a binomial random variable. By (1.7) in [15], for large enough n,

$$P\left(|\mathcal{X}_n \cap S_i| \ge 21\alpha_n\right) \le \exp\left(\frac{-21\alpha_n}{2}\log\left(\frac{21\alpha_n}{E\left[|\mathcal{X}_n \cap S_i|\right]}\right)\right)$$
$$\le \exp\left(\frac{-21n}{2(\frac{\sqrt{5}}{r_n} + 1)^2}\log\left(21\right)\right)$$
$$< \exp(-2.03 \cdot \log n) = n^{-2.03}.$$

Thus, by the definition of Δ_n , for large enough n we have

$$P\left(\Delta_n \ge 21\alpha_n\right) = P\left(\bigcup_{i=1}^{K_n^2} \{|\mathcal{X}_n \cap S_i| \ge 21\alpha_n\}\right)$$
$$\le \sum_{i=1}^{K_n^2} P\left(|\mathcal{X}_n \cap S_i| \ge 21\alpha_n\right)$$
$$< n \cdot n^{-2.03} = n^{-1.03}.$$

Hence, using the Borel–Cantelli lemma yields our result.

Remark 4.2. Using a method similar to that of Theorem 6.14 in [15], we can get that, with probability 1, the inequality

$$\alpha_n H_+^{-1}\left(\frac{\log n}{\alpha_n}\right)(1-o(1)) \le \Delta_n \le \alpha_n H_+^{-1}\left(\frac{\log n}{\alpha_n}\right)(1+o(1))$$

holds for large n. However, the proof of this result is complicated, so we do not include it in this paper.

In the following we need to introduce some definitions. Let $\|\cdot\|_1$ denote the l_1 -norm, and let $\|\cdot\|_{\infty}$ denote the infinity norm. For any $x, y \in \mathbb{Z}^2$, if $\|x - y\|_1 = 1$, then we say that x and y are *adjacent*, and we write $x \sim y$. Also, given $A \subseteq \mathbb{Z}^2$, if for any $x, y \in A$, there exists a vertex sequence x_1, x_2, \ldots, x_n in A such that $x \sim x_1, x_1 \sim x_2, x_2 \sim x_3, \ldots, x_n \sim y$, then we say A is connected. Similarly, if



FIG. 2. A_i and A_j are the connected components surrounded by the solid lines. If $A_i \cup A_j$ is 3-connected, then there exist $z_i \in \partial A_i$ and $z_j \in \partial A_j$ such that $z_i \sim_3 z_j$, and there exist $\tilde{z_i} \in \partial(A_i^c)$ and $\tilde{z_j} \in \partial(A_j^c)$ such that $\tilde{z_i} \sim_2 \tilde{z_j}$.

 $||x - y||_{\infty} \leq k, k \geq 1$, we say that x and y are k-adjacent, and we write $x \sim_k y$. Given $A \subseteq \mathbb{Z}^2$, if for any $x, y \in A$, there exists a vertex sequence x_1, x_2, \ldots, x_n in A such that $x \sim_k x_1, x_1 \sim_k x_2, x_2 \sim_k x_3, \ldots, x_n \sim_k y$, then we say A is k-connected. It can be seen that if A is connected, then A must be k-connected for all $k \geq 1$. In particular, a single vertex set $\{x\} \subset \mathbb{Z}^2$ is both connected and k-connected.

We define the lattice box $B_{\mathbb{Z}}(K_n)$ by $B_{\mathbb{Z}}(K_n) := \prod_{i=1}^2 ([1, K_n] \cap \mathbb{Z})$. If $A \subset B_{\mathbb{Z}}(K_n)$, set $A^c := B_{\mathbb{Z}}(K_n) \setminus A$, and let ∂A denote the *internal vertex-boundary* of A, that is, the set of vertex $z \in A$ such that $\{y \in A^c : ||z - y||_1 = 1\}$ is nonempty. To prove Theorem 3.3, several lemmas are needed.

LEMMA 4.3. Let $\beta \in (0,1)$. If A is a subset of $B_{\mathbb{Z}}(K_n)$ (not necessarily connected), with $|A| \leq \beta K_n^2$, then

$$|\partial A| \ge \frac{1}{4}(1-\sqrt{\beta})\sqrt{|A|}.$$

Proof. Replacing 2/3 with β into the proof of Lemma 9.9 of [15], the result can be deduced.

LEMMA 4.4 (Lemma 9.6 in [15]). Suppose $A \subset B_{\mathbb{Z}}(K_n)$ is such that both A and A^c are connected. Then ∂A is 1-connected.

Remark 4.5. If both A and A^c are connected, by Lemma 4.4 both ∂A and $\partial (A^c)$ are 1-connected since $(A^c)^c = A$.

LEMMA 4.6. Suppose $A \subset B_{\mathbb{Z}}(K_n)$. If A is 3-connected and A^c is connected, then ∂A is 3-connected, and $\partial(A^c)$ is 2-connected.

Proof. Let A_1, A_2, \ldots, A_m denote the connected components of A, which indicates that A_1, \ldots, A_m are connected, but $A_i \cup A_j$, $1 \le i \ne j \le m$, is not connected. By the fact that $B_{\mathbb{Z}}(K_n)$ is connected, $A_i, i \in [1, m]$, are all connected with A^c . Note that A^c is connected, so for any $i \in [1, m]$, $A_i^c = A^c \cup A_1 \cup \cdots \cup A_{i-1} \cup A_{i+1} \cup A_m$ is also connected. By Lemma 4.4, we know that both ∂A_i and $\partial (A_i^c)$ are 1-connected.

Moreover, if $A_i \cup A_j (i \neq j)$ is 3-connected, then there exists a pair $(z_i, z_j) \in (\partial A_i, \partial A_j)$ such that z_i and z_j are 3-connected, and there exists another pair $(\tilde{z}_i, \tilde{z}_j) \in (\partial (A_i^c), \partial (A_j^c))$ such that \tilde{z}_i and \tilde{z}_j are 2-connected; see Figure 2. Thus, $\partial A_i \cup \partial A_j$ is 3-connected, and $\partial (A_i^c) \cup \partial (A_j^c)$ is 2-connected since $\partial A_i, \partial A_j, \partial (A_i^c)$, and $\partial (A_j^c)$ are 1-connected. Combining this with the fact that $A = \bigcup_{i=1}^m A_i$ is 3-connected, we have that $\partial A = \bigcup_{i=1}^m \partial A_i$ is 3-connected, and $\partial (A^c) = \bigcup_{i=1}^m \partial (A_i^c)$ is 2-connected. \Box



FIG. 3. The relationships of S_i , x_i , and z_i are shown. If $z_i \sim z_j$, then any two vertices x, y in $S_i \cup S_j$ will satisfy $||x - y||_2 \le r_n$.

LEMMA 4.7 (Corollary 9.4 in [15]). Given integer $k \ge 1$, the number of kconnected subsets of the lattice box $B_{\mathbb{Z}}(K_n)$ of cardinality m is at most $K_n^2 2^{4k(k+1)m}$.

For each small square S_i , $1 \le i \le K_n^2$, let x_i denote its center point. Set $z_i :=$ $K_n x_i + \frac{1}{2} \in \mathbb{Z}^2$; see Figure 3. By the definition of $B_{\mathbb{Z}}(K_n)$, we can get that the set $\{z_i: 1 \leq i \leq K_n^2\}$ is equal to $B_{\mathbb{Z}}(K_n)$. Recall that $\lambda(n) = n - n^{3/4}$, and $\mathcal{P}_{\lambda(n)}$ denotes a Poisson point process in $[0, 1]^2$

with parameter $\lambda(n)$. Define the function

$$f_1(A) := \sum_{z_i \in A, z_j \in A^c, z_i \sim z_j} |\mathcal{P}_{\lambda(n)} \cap S_i| \cdot |\mathcal{P}_{\lambda(n)} \cap S_j|;$$

we can get the following lemmas.

LEMMA 4.8. Assume that r_n satisfies (4.1). Suppose $A \subset B_{\mathbb{Z}}(K_n)$ and integer $k \geq 1$. Then for any constant $\beta \in (0,1)$, there exists a constant $\eta = \eta(k,\beta) > 0$ such that for large enough n,

$$P\left[\inf_{\substack{\beta \alpha_n^{-2} \kappa_n \leq |A| \leq (1-\beta) \kappa_n^2 \\ \partial A \text{ is } k-connected}} \frac{f_1(A)}{|A|} \leq \frac{\eta \alpha_n^2}{K_n}\right] < e^{-n^{1/5}}.$$

Proof. This proof partly uses the ideas appearing in [18]. Let

$$c_1 := \frac{1 - \sqrt{1 - \beta}}{4\sqrt{1 - \beta}}$$
 and $c_2 := \frac{1}{4}(1 - \sqrt{1 - \beta})\sqrt{\beta}$

If $\beta \alpha_n^{-2} K_n \leq |A| \leq (1-\beta) K_n^2$, then by Lemma 4.3,

(4.2)
$$|\partial A| \ge \frac{1}{4}(1 - \sqrt{1 - \beta})\sqrt{|A|} \ge \frac{c_1|A|}{K_n},$$

and also

(4.3)
$$|\partial A| \ge \frac{1}{4} (1 - \sqrt{1 - \beta}) \sqrt{|A|} \ge \frac{c_2 \sqrt{K_n}}{\alpha_n}$$

For any $\varepsilon > 0$, by the definition of f_1 we can get

$$(4.4) \qquad f_1(A) \ge (\varepsilon \alpha_n)^2 \sum_{z_i \in \partial A, z_j \in \partial (A^c), z_i \sim z_j} I_{\{|\mathcal{P}_{\lambda(n)} \cap S_i| \ge \varepsilon \alpha_n, |\mathcal{P}_{\lambda(n)} \cap S_j| \ge \varepsilon \alpha_n\}}.$$

For any set $\Lambda, \Gamma \subset B_{\mathbb{Z}}(K_n)$, let

$$\xi(\Lambda,\Gamma) := \sum_{z_i \in \Lambda, z_j \in \Gamma, z_i \sim z_j} I_{\{|\mathcal{P}_{\lambda(n)} \cap S_i| \ge \varepsilon \alpha_n, |\mathcal{P}_{\lambda(n)} \cap S_j| \ge \varepsilon \alpha_n\}}$$

Therefore, by (4.2) and (4.4) we have

$$\frac{f_1(A)}{|A|} \ge \frac{c_1(\varepsilon \alpha_n)^2 \xi(\partial A, \partial(A^c))}{K_n |\partial A|}$$

Combining the above inequality with (4.3) yields

(4.5)
$$\frac{\inf_{\substack{\beta \alpha_n^{-2} K_n \le |A| \le (1-\beta) K_n^2 \\ \partial A \text{ is } k \text{-connected}}} \frac{f_1(A)}{|A|}}{\sum_{\substack{\beta A \text{ is } k \text{-connected} \\ \partial A \text{ is } k \text{-connected}}} \inf_{\substack{\{\partial A \mid \ge c_2 \alpha_n^{-1} \sqrt{K_n} \\ \partial A \text{ is } k \text{-connected}}} \frac{\xi(\partial A, \partial(A^c))}{|\partial A|}.$$

Note that for any $z \in \partial(A^c)$, there exists at least one vertex $\tilde{z} \in \partial A$ such that $z \sim \tilde{z}$, so if ∂A is k-connected, then $\partial A \cup \partial(A^c)$ is also k-connected. Let $(\Lambda_1^{M,m}, \Gamma_1^{M,m}), (\Lambda_2^{M,m}, \Gamma_2^{M,m}), \ldots, (\Lambda_{i_{M,m}}^{M,m}, \Gamma_{i_{M,m}}^{M,m})$ denote all possible pairs of $(\partial A, \partial(A^c))$ satisfying (i) ∂A is k-connected, (ii) $|\partial A \cup \partial(A^c)| = M$, and (iii) $|\partial A| = m$. Then by Lemma 4.7,

(4.6)
$$\sum_{m=1}^{M} i_{M,m} \leq K_n^2 2^{4k(k+1)M} \sum_{m=1}^{M} \binom{M}{m} = K_n^2 2^{4k(k+1)M} \cdot 2^M = K_n^2 2^{(2k+1)^2M}.$$

Thus, for any constant $c_3 > 0$, using Boole's inequality we can get

$$P\left(\inf_{\substack{|\partial A| \ge c_2 \alpha_n^{-1} \sqrt{K_n} \\ \partial A \text{ is } k \text{-connected}}} \frac{\xi(\partial A, \partial(A^c))}{|\partial A|} \le c_3\right)$$

$$= P\left(\bigcup_{m \ge c_2 \alpha_n^{-1} \sqrt{K_n}} \bigcup_{M \ge m} \bigcup_{l=1}^{i_{M,m}} \left\{\frac{\xi(\Lambda_l^{M,m}, \Gamma_l^{M,m})}{m} \le c_3\right\}\right)$$

$$\leq P\left(\bigcup_{M \ge c_2 \alpha_n^{-1} \sqrt{K_n}} \bigcup_{m=1}^M \bigcup_{l=1}^{i_{M,m}} \left\{\frac{\xi(\Lambda_l^{M,m}, \Gamma_l^{M,m})}{M} \le c_3\right\}\right)$$

$$\leq \sum_{M \ge c_2 \alpha_n^{-1} \sqrt{K_n}} \sum_{m=1}^M \sum_{l=1}^{i_{M,m}} P\left(\xi(\Lambda_l^{M,m}, \Gamma_l^{M,m}) \le c_3M\right).$$

For any $z \in \Lambda_l^{M,m}$ (or $\Gamma_l^{M,m}$), $1 \leq l \leq i_{M,m}$, there exist at least one and at most four vertices in $\Gamma_l^{M,m}$ (or $\Lambda_l^{M,m}$) which are connected with z, and thus we can choose the vertex pairs $(z_{i_1}, z_{i_1}), (z_{i_2}, z_{i_2}), \ldots, (z_{i_{j(l)}}, z_{i_{j(l)}}) \in (\Lambda_l^{M,m}, \Gamma_l^{M,m}), \ j(l) \geq M/8$, such that $z_{i_1} \sim z_{i_1}, z_{i_2} \sim z_{i_2}, \ldots, z_{i_{j(l)}} \sim z_{i_{j(l)}}$ and $z_{i_1}, z_{i_1}, z_{i_2}, z_{i_2}, \ldots, z_{i_{j(l)}}, z_{i_{j(l)}}$ are mutually different. Thus, by the spatial independence of the Poisson point process, for any $1 \leq k_1 \neq k_2 \leq j(l)$, the corresponding events $I_{\{|\mathcal{P}_{\lambda(n)} \cap S_{i_{k_1}}| \geq \varepsilon \alpha_n, |\mathcal{P}_{\lambda(n)} \cap S_{i_{k_1}}| \geq \varepsilon \alpha_n\}}$ and $I_{\{|\mathcal{P}_{\lambda(n)} \cap S_{i_{k_2}}| \geq \varepsilon \alpha_n, |\mathcal{P}_{\lambda(n)} \cap S_{i_{k_2}}| \geq \varepsilon \alpha_n\}}$ are mutually independent. Let $E_k = I_{\{|\mathcal{P}_{\lambda(n)} \cap S_{i_k}| \geq \varepsilon \alpha_n, |\mathcal{P}_{\lambda(n)} \cap S_{i_k}| \geq \varepsilon \alpha_n\}}$; then

(4.8)
$$P\left(\xi(\Lambda_l^{M,m},\Gamma_l^{M,m}) \le c_3M\right) \le P\left(\sum_{k=1}^{j(l)} E_k \le c_3M\right),$$

where $j(l) \ge M/8$ and the events E_k , $1 \le k \le j(l)$, are mutually independent. Choose $\varepsilon = 1/2$; then for all large n and $1 \le k \le j(l)$,

$$P(E_k) = P\left(\left|\mathcal{P}_{\lambda(n)} \cap S_{i_k}\right| \ge \frac{\alpha_n}{2}\right) P\left(\left|\mathcal{P}_{\lambda(n)} \cap S_{\tilde{i_k}}\right| \ge \frac{\alpha_n}{2}\right)$$
$$= P^2\left(Po\left(\frac{n-n^{3/4}}{\lceil \frac{\sqrt{5}}{r_n} \rceil^2}\right) \ge \frac{\alpha_n}{2}\right)$$
$$\ge \left(1 - \exp\left\{-\frac{n-n^{3/4}}{\lceil \frac{\sqrt{5}}{r_n} \rceil^2} H\left(\frac{\alpha_n \lceil \frac{\sqrt{5}}{r_n} \rceil^2}{2(n-n^{3/4})}\right)\right\}\right)^2$$
$$\ge \left(1 - \exp\left\{-\frac{\log n}{5} H\left(\frac{2}{3}\right)\right\}\right)^2 = \left(1 - n^{-H(\frac{2}{3})/5}\right)^2,$$

where the last inequality follows from Lemma 1.2 in [15]. Therefore, for any $\rho > 0$ and large enough n, by Markov's inequality we have

(4.9)

$$P\left(\sum_{k=1}^{j(l)} E_k \le c_3 M\right) = P\left(\exp\left(-\rho \sum_{k=1}^{j(l)} E_k\right) \ge e^{-\rho c_3 M}\right)$$

$$\leq e^{\rho c_3 M} \prod_{k=1}^{j(l)} E\left[e^{-\rho E_k}\right]$$

$$\leq e^{\rho c_3 M} \left(\left(1 - n^{-H(\frac{2}{3})/5}\right)^2 e^{-\rho} + 1 - \left(1 - n^{-H(\frac{2}{3})/5}\right)^2\right)^{M/8}.$$

Choose $c_3 > 0$ small enough; then there exist constants $\rho > 0$ and $c_4 > 0$ such that for large enough n,

(4.10)
$$(2k+1)^2 \log 2 + \rho c_3 \\ + \frac{1}{8} \log \left(\left(1 - n^{-H(\frac{2}{3})/5} \right)^2 e^{-\rho} + 1 - \left(1 - n^{-H(\frac{2}{3})/5} \right)^2 \right) \le -c_4.$$

Combining (4.6)–(4.9) with (4.10), for large enough n we have

$$P\left(\inf_{\substack{|\partial A| \ge c_2 \alpha_n^{-1} \sqrt{K_n} \\ \partial A \text{ is } k \text{-connected}}} \frac{\xi(\partial A, \partial(A^c))}{|\partial A|} \le c_3\right)$$
$$\le \sum_{M \ge c_2 \alpha_n^{-1} \sqrt{K_n}} \sum_{m=1}^M \sum_{l=1}^{i_{M,m}} P\left(\sum_{k=1}^{j(l)} E_k \le c_3 M\right)$$

$$\leq \sum_{M \geq c_2 \alpha_n^{-1} \sqrt{K_n}} K_n^2 2^{(2k+1)^2 M} e^{\rho c_3 M} \\ \cdot \left(\left(1 - n^{-H(\frac{2}{3})/5} \right)^2 e^{-\rho} + 1 - \left(1 - n^{-H(\frac{2}{3})/5} \right)^2 \right)^{M/8} \\ \leq \sum_{M \geq c_2 \alpha_n^{-1} \sqrt{K_n}} K_n^2 e^{-c_4 M} \leq \exp\left(\frac{-c_4 c_2 \alpha_n^{-1} \sqrt{K_n}}{2} \right) < e^{-n^{1/5}}.$$

The above inequality and (4.5) yield our result.

For any $z_i \in B_{\mathbb{Z}}(K_n)$, we call z_i open if $S_i \cap \mathcal{P}_{\lambda(n)} \neq \emptyset$ and call z_i closed otherwise. Let \mathcal{O}_n denote the set of open vertices in $B_{\mathbb{Z}}(K_n)$, and let \mathcal{C}_n denote the largest open clusters of \mathcal{O}_n .

LEMMA 4.9. Assume that r_n satisfies (4.1). Then with probability 1, $|\mathcal{C}_n| = (1 - o(1))K_n^2$ for all large enough n.

Proof. For any $z \in B_{\mathbb{Z}}(K_n)$,

$$P(\{z \text{ is closed}\}) = \exp\left(-\frac{\lambda(n)}{K_n^2}\right) \to 0 \text{ as } n \to \infty$$

By Theorem 8.65 in [19] and Theorem 1 in [20] our result can be deduced.

LEMMA 4.10. Assume that r_n satisfies (4.1). Suppose $A \subset B_{\mathbb{Z}}(K_n)$. Then for any constant $\beta \in (0,1)$, there exists a constant $\eta = \eta(\beta) > 0$ such that for large enough n,

$$\inf_{\substack{\beta \propto_n^{-2} K_n \le |A| \le (1-\beta) K_n^2 \\ A \text{ is } 3-connected}} \frac{f_1(A)}{|A|} \ge \frac{\eta \alpha_n^2}{K_n} \qquad a.s.$$

Proof. For any $A \subset B_{\mathbb{Z}}(K_n)$ with $\beta \alpha_n^{-2} K_n \leq |A| \leq (1-\beta)K_n^2$, let $\Lambda_1, \ldots, \Lambda_{m_A}$ denote the connected components of A^c , taken in decreasing order. In other words, $\Lambda_1, \ldots, \Lambda_{m_A}$ are connected, but $\Lambda_i \cup \Lambda_j$, $1 \leq i \neq j \leq m_A$, is not connected, and $|\Lambda_1| \geq |\Lambda_2| \geq \cdots \geq |\Lambda_{m_A}|$. Since $\Lambda_1, \ldots, \Lambda_{m_A}$ are all connected with A, and A is 3-connected, Λ_i^c , $1 \leq i \leq m_A$ are all 3-connected. By Lemma 4.6, for $1 \leq i \leq m_A$, $\partial(\Lambda_i^c)$ is 3-connected and $\partial\Lambda_i$ is 2-connected. By the definition of f_1 we can get

(4.11)
$$f_1(A) = \sum_{i=1}^{m_A} f_1(\Lambda_i) = \sum_{i=1}^{m_A} f_1(\Lambda_i^c).$$

If $|\Lambda_1| > K_n^2/2$, then $|\Lambda_1^c| \le K_n^2/2$. Note that $A \subseteq \Lambda_1^c$, and by (4.11) and Lemma 4.8 we have

(4.12)
$$\frac{\inf_{\substack{|A| \ge \beta \alpha_n^{-2} K_n, |\Lambda_1| > \frac{1}{2} K_n^2 \\ A \text{ is 3-connected}}}{\sum_{\substack{|A| \ge \beta \alpha_n^{-2} K_n \le |\Lambda_1^c| \le \frac{1}{2} K_n^2 \\ \partial (\Lambda_1^c) \text{ is 3-connected}}} \frac{f_1(\Lambda_1^c)}{|\Lambda_1^c|} > \frac{\eta \alpha_n^2}{K_n} \quad \text{a.s.}$$

Next we consider the case of $|\Lambda_1| \leq K_n^2/2$. Without loss of generality, we assume that $|\Lambda_i| \geq \frac{1}{2}\alpha_n^{-2}K_n$ for $1 \leq i \leq i_A$, and $|\Lambda_i| < \frac{1}{2}\alpha_n^{-2}K_n$ for $i_A + 1 \leq i \leq m_A$, where

 $i_A \in [1, m_A]$. Since $\partial \Lambda_i$ is 2-connected, by Lemma 4.8 and the Borel–Cantelli lemma, with probability 1,

$$\frac{f_1(\Lambda_i)}{|\Lambda_i|} > \frac{\eta \alpha_n^2}{K_n} \quad \forall 1 \le i \le i_A$$

for all large n. Thus,

(4.13)
$$\begin{array}{l} \inf_{\substack{A \text{ is 3-connected,} |\Lambda_1| \leq \frac{1}{2}K_n^2} \frac{\sum_{i=1}^{i_A} f_1(\Lambda_i)}{\sum_{i=1}^{i_A} |\Lambda_i|} \\ \geq \min_{\substack{1 \leq i \leq i_A}} \left\{ \inf_{\substack{\frac{1}{2}\alpha_n^{-2}K_n \leq |\Lambda_i| \leq \frac{1}{2}K_n^2, \\ \partial \Lambda_i \text{ is 2-connected}}} \frac{f_1(\Lambda_i)}{|\Lambda_i|} \right\} > \frac{\eta \alpha_n^2}{K_n} \quad \text{a.s.}
\end{array}$$

holds for large enough n.

For Λ_i , $i_A + 1 \leq i \leq m_A$, if $\Lambda_i \cap \mathcal{C}_n \neq \emptyset$, then $f_1(\Lambda_i) \geq 1$, which indicates that

(4.14)
$$\frac{f_1(\Lambda_i)}{|\Lambda_i|} > \frac{1}{\frac{1}{2}\alpha_n^{-2}K_n} = \frac{2\alpha_n^2}{K_n}$$

Let $\eta' := \min\{\eta, 2\}$. By (4.13) and (4.14) we can get, with probability 1,

(4.15)
$$\inf_{\substack{A \text{ is 3-connected}, |\Lambda_1| \leq \frac{1}{2}K_n^2 \\ \geq \frac{\eta' \alpha_n^2}{K_n}} \frac{\sum_{i=1}^{i_A} f_1(\Lambda_i) + \sum_{i_A+1 \leq i \leq m_A, \Lambda_i \cap \mathcal{C}_n \neq \emptyset} f_1(\Lambda_i)}{\left(\sum_{i=1}^{i_A} + \sum_{i_A+1 \leq i \leq m_A, \Lambda_i \cap \mathcal{C}_n \neq \emptyset}\right) |\Lambda_i|}$$

For the case of $\Lambda_i \cap \mathcal{C}_n = \emptyset$, by Lemma 4.9, for large enough n,

$$\sum_{i_A+1\leq i\leq m_A,\Lambda_i\cap \mathcal{C}_n=\emptyset} |\Lambda_i|\leq K_n^2-|\mathcal{C}_n|=o(K_n^2) \quad \text{a.s.}$$

Moreover, note that $\sum_{i=1}^{m_A} |\Lambda_i| = |A^c| \ge \beta K_n^2$, so we have

$$\begin{pmatrix} i_A \\ \sum_{i=1}^{i_A} + \sum_{i_A+1 \le i \le m_A, \Lambda_i \cap \mathcal{C}_n \neq \emptyset} \end{pmatrix} |\Lambda_i| \\ = |A^c| - \sum_{i_A+1 \le i \le m_A, \Lambda_i \cap \mathcal{C}_n = \emptyset} |\Lambda_i| \ge \frac{\beta}{2} K_n^2 \quad \text{a.s.}$$

Combining the above inequality with (4.11) and (4.15), for large enough n, we have

$$\inf_{\substack{|A| \le (1-\beta)K_n^2, |\Lambda_1| \le \frac{1}{2}K_n^2 \\ A \text{ is 3-connected}}} f_1(A) \ge \frac{\eta' \alpha_n^2}{K_n} \cdot \frac{\beta K_n^2}{2} = \frac{\eta' \beta \alpha_n^2 K_n}{2} \qquad \text{a.s.}$$

By the above inequality, we can deduce that, with probability 1,

$$\inf_{\substack{|A| \le (1-\beta)K_n^2, |\Lambda_1| \le \frac{1}{2}K_n^2 \\ A \text{ is 3-connected}}} \frac{f_1(A)}{|A|} \ge \frac{\eta' \beta \alpha_n^2 K_n}{2} \cdot \frac{1}{(1-\beta)K_n^2} = \frac{\eta' \beta \alpha_n^2}{2(1-\beta)K_n}$$

for large n. Combining this with (4.12) yields our result.

Recall that d_i denotes the degree of vertex i in G(0), and set $d^* := \sum_{i=1}^n d_i$. We can get the following lemma.

LEMMA 4.11. Assume that r_n satisfies (4.1). Then for any constant $s > 1/\pi$, with probability 1, $d^* > n^2 r_n^2/s$ for large enough n.

Proof. Given a constant $s' \in (1/\pi, s)$, let $Z_n(s')$ denote the number of vertices of G(0) of degree at least nr_n^2/s' . By Theorem 4.2 in [15], $n^{-1}Z_n(s')$ converges completely to 1 as $n \to \infty$. Since $d^* \ge Z_n(s')nr_n^2/s'$, this yields our result.

Proof of Theorem 3.3. If G(0) is not connected, then P(0) is reducible and therefore $\lambda_2 = 1$, so our necessary condition can be deduced directly by Lemma 2.1. Also, for the case of $\pi n r_n^2 \ge (\log n)^2$, our sufficient condition has been indicated by (3.3). Thus, we just need to consider the sufficient condition for the case that r_n satisfies (4.1).

Given $\lambda \in \mathbb{R}$, if $\lambda < \frac{1}{d_{max}} - 1$, then $P(0) - \lambda I_n$ is a strictly diagonally dominant matrix and det $(P(0) - \lambda I_n) \neq 0$. Therefore λ is not an eigenvalue of P(0). By Lemma 3.1 we can get that for all large enough n, with probability 1,

$$\lambda_n \ge \frac{1}{e\pi n r_n^2 (1+o(1))} - 1.$$

Note that $1 \ge \lambda_2 \ge \lambda_n \ge -1$, so we just need to estimate λ_2 to get our result.

Let $F \subseteq \{1, 2, ..., n\}$ denote a subset of agents and define $F := \{X_i(0) : i \in F\} \subseteq \mathcal{X}_n$ to be the initial positions of agents in F. Let $F^c = \{1, 2, ..., n\} \setminus F$. For any area $D_1, D_2 \subset [0, 1]^2$, set

$$f_{D_1,D_2}(F) := \sum_{x \in D_1 \cap \widetilde{F}, y \in D_2 \cap \widetilde{F^c}} I_{\{\|x-y\|_2 \le r_n\}}$$

and take $f(F) = f_{[0,1]^2,[0,1]^2}(F)$. Define Cheeger's constant Φ of P(0) by

$$\Phi = \inf_{\sum_{i \in F} d_i \le \frac{1}{2}d^*} \frac{f(F)}{\sum_{i \in F} d_i}.$$

We assert that there exists a constant $\eta > 0$ such that w.h.p., $\Phi \ge \eta r_n$ for large enough n. Next we will prove this assertion.

For any $F \subseteq \{1, 2, \ldots, n\}$, set

$$A_F := \left\{ z_i : |S_i \cap \widetilde{F}| > \frac{1}{2} |S_i \cap \mathcal{X}_n| \right\} \subseteq B_{\mathbb{Z}}(K_n),$$

and define

$$\widetilde{A_F} := \bigcup_{z_i \in A_F} S_i \cap \mathcal{X}_n.$$

By the condition of $\sum_{i \in F} d_i \leq \frac{1}{2}d^*$, we have

$$|F^c|d_{\max} \ge \sum_{i \in F^c} d_i \ge \frac{1}{2}d^*;$$

then by Corollary 3.2 and Lemma 4.11, for all large enough n,

$$|F^c| \ge \frac{d^*}{2d_{\max}} > \frac{2e\pi n^2 r_n^2}{6} \cdot \frac{1}{2e\pi n r_n^2} = \frac{n}{6}$$
 a.s.

Set
$$\beta := \frac{1}{252}$$
. If $|A_F| > (1 - \beta)K_n^2$, then $|A_F^c| \le \beta K_n^2$. By Lemma 4.1,

$$\sum_{z_i \in A_F^c} |S_i| \le |A_F^c| \Delta_n \le \frac{K_n^2}{252} \cdot 21\alpha_n = \frac{n}{12}$$

holds almost surely for large enough n. Note that $|\widetilde{F^c}| = |F^c| > \frac{n}{6}$; then there exist at least $\frac{n}{12}$ vertices of $\widetilde{F^c}$ contained in $\widetilde{A_F}$. For $x \in \widetilde{F^c} \cap \widetilde{A_F}$, without loss of generality we assume that $x \in S_i$ with $z_i \in A_F$; then by the definition of A_F we can get $|\widetilde{F} \cap S_i| \geq |\widetilde{F^c} \cap S_i| \geq 1$, which indicates that there exists at least one vertex $y \in \widetilde{F} \cap S_i$ such that $||x - y||_2 \leq r_n$. Thus, by Lemma 3.1,

(4.16)
$$\begin{split} \inf_{\sum_{i \in F} d_i \leq \frac{1}{2} d^*, |A_F| > (1-\beta) K_n^2} \frac{f(F)}{\sum_{i \in F} d_i} \geq \frac{\frac{n}{12}}{\frac{1}{2} n d_{\max}} \\ \geq \frac{1}{6e\pi n r_n^2 (1+o(1))} > r_n \end{split}$$

holds almost surely for large enough n.

Now, we will consider the case of $|A_F| \leq (1-\beta)K_n^2$. Let $A_1, A_2, \ldots, A_{m_F}$ be the 3-connected components of A_F , taken in decreasing order of size. In other words, A_1, \ldots, A_{m_F} are all 3-connected, but $A_i \cup A_j$, $1 \leq i \neq j \leq m_F$, is not 3-connected, and $|A_1| \geq |A_2| \geq \cdots \geq A_{m_F}$. Without loss of generality, we assume that $|A_i| \geq \beta \alpha_n^{-2} K_n$ for $1 \leq i \leq i_F$, and $|A_i| < \beta \alpha_n^{-2} K_n$ for $i_F + 1 \leq i \leq m_F$, where $i_F \in [1, m_F]$. Then by Lemma 4.10, there exists a constant $\eta' > 0$ such that

(4.17)
$$\inf_{|A_F| \le (1-\beta)K_n^2, 1 \le i \le i_F} \frac{f_1(A_i)}{|A_i|} \ge \frac{\eta' \alpha_n^2}{K_n} \quad \text{a.s.}$$

For $i \in [1, i_F]$, it is easy to see that if $z_k \in A_i$ and $z_j \in A_i^c$ with $z_k \sim z_j$, then $z_j \in A_F^c$, and all pairs of vertices in $S_k \cup S_j$ are neighbors. So by the definition of A_F , we have

$$f_{S_k,S_j}(F) = \sum_{x \in S_k \cap \widetilde{F}, y \in S_j \cap \widetilde{F^c}} I_{\{\|x-y\|_2 \le r_n\}} \ge \frac{1}{4} |\mathcal{X}_n \cap S_k| \cdot |\mathcal{X}_n \cap S_j|.$$

Therefore, if $\mathcal{P}_{\lambda(n)} \subseteq \mathcal{X}_n$, then

(4.18)
$$\sum_{z_k \in A_i, z_j \in A_F^c, z_k \sim z_j} f_{S_k, S_j}(F) = \sum_{z_k \in A_i, z_j \in A_i^c, z_k \sim z_j} f_{S_k, S_j}(F) \ge \frac{1}{4} f_1(A_i).$$

Moreover, by (3.12) and the Borel–Cantelli lemma, we know that $\mathcal{P}_{\lambda(n)} \subseteq \mathcal{X}_n$ holds almost surely for large enough n. Set

$$S_F^1 := \bigcup_{i=1}^{i_F} \bigcup_{z_k \in A_i} S_k$$

By (4.18), for large enough n, we have

(4.19)
$$f_{S_{F}^{1},[0,1]^{2}\setminus S_{F}^{1}}(F) \geq \sum_{i=1}^{i_{F}} \sum_{z_{k}\in A_{i}, z_{j}\in A_{F}^{c}, z_{k}\sim z_{j}} f_{S_{k},S_{j}}(F)$$
$$\geq \sum_{i=1}^{i_{F}} \frac{1}{4} f_{1}(A_{i}) \quad \text{a.s.}$$

For $i \in [i_F + 1, m_F]$, if $\bigcup_{z_j \in A_i} S_j \cap \widetilde{F^c} \neq \emptyset$, let $D_i = \bigcup_{z_j \in A_i} S_j$. Then we have $f_{D_i, D_i}(F) \ge 1$; otherwise, by Lemma 2.1, with high probability there exists at least one vertex $x^* \in (\bigcup_{z_j \in A_i} S_j)^c \cap \mathcal{X}_n$ such that the set

$$\left\{ y: y \in \bigcup_{z_j \in A_i} S_j \cap \widetilde{F}, \|x^* - y\| \le r_n \right\}$$

is not empty. Assume that $x^* \in S_k (1 \leq k \leq K_n^2)$ and z_k is the corresponding integer point of S_k . Then z_k must be 3-connected with A_i , and $z_k \in A_F^c$. Set $D_i = \bigcup_{z_j \in A_i} S_j \cup S_k$. If $x^* \in \widetilde{F^c}$, then $f_{D_i,D_i}(F) \geq 1$; otherwise, by the definition of A_F we have $S_k \cap \widetilde{F^c} \neq \emptyset$, so

$$f_{D_i,D_i}(F) \ge f_{S_k,S_k}(F) \ge 1.$$

Let $S_F^2 = \bigcup_{i=i_F+1}^{m_F} D_i$. For $z \in \mathbb{Z}^2$, it is easy to see that the number of 3-connected components that z is 3-connected with is not more than 8. By the above argument we have w.h.p.

(4.20)
$$f_{S_F^2, S_F^2}(F) \ge \frac{1}{8}(m_F - i_F).$$

Let $S_F^3 = [0,1]^2 \setminus (S_F^1 \cup S_F^2)$. For $x \in S_F^3 \cap \widetilde{F}$, assume that $x \in S_k (1 \le k \le K_n^2)$ and $z_k \in B_{\mathbb{Z}}(K_n)$ is the corresponding integer point of S_k . Obviously $z_k \in A_F^c$, so the set $S_k \cap \widetilde{F^c}$ is not empty. Thus,

(4.21)
$$f_{S^3_F, S^3_F}(F) \ge \sum_{x \in S^3_F \cap \widetilde{F}} 1 \ge |S^3_F \cap \widetilde{F}|.$$

Recall that $\mathcal{L}(\cdot)$ denotes the Lebesgue measure. By the definitions of S_F^1 and S_F^2 we have $\mathcal{L}(S_F^1 \cap S_F^2) = 0$. So by (4.19), (4.20), and (4.21), we have

$$\begin{split} f(F) &\geq f_{S_F^1,[0,1]^2 \setminus S_F^1}(F) + f_{S_F^2,S_F^2}(F) + f_{S_F^3,S_F^3}(F) \\ &\geq \sum_{i=1}^{i_F} \frac{1}{4} f_1(A_i) + \frac{1}{8} (m_F - i_F) + |S_F^3 \cap \widetilde{F}| \quad \text{w.h.p.} \end{split}$$

Thus, w.h.p.,

j

$$\begin{aligned} \inf_{|A_{F}| \leq (1-\beta)K_{n}^{2}} \frac{f(F)}{\sum_{i \in F} d_{i}} \\ &\geq \frac{\sum_{i=1}^{i_{F}} \frac{1}{4} f_{1}(A_{i}) + \frac{1}{8}(m_{F} - i_{F}) + |S_{F}^{3} \cap \widetilde{F}|}{d_{\max}(|S_{F}^{1} \cap \widetilde{F}| + |S_{F}^{2} \cap \widetilde{F}| + |S_{F}^{3} \cap \widetilde{F}|)} \\ (4.22) &\geq \frac{\sum_{i=1}^{i_{F}} \frac{1}{4} f_{1}(A_{i}) + \frac{1}{8}(m_{F} - i_{F}) + |S_{F}^{3} \cap \widetilde{F}|}{d_{\max}(\Delta_{n} \sum_{i=1}^{i_{F}} |A_{i}| + (m_{F} - i_{F})\Delta_{n}\beta\alpha_{n}^{-2}K_{n} + |S_{F}^{3} \cap \widetilde{F}|)} \\ &\geq \min\left\{\frac{\frac{1}{4} \sum_{i=1}^{i_{F}} f_{1}(A_{i})}{d_{\max}\Delta_{n} \sum_{i=1}^{i_{F}} |A_{i}|}, \frac{\frac{1}{8}(m_{F} - i_{F})}{d_{\max}(m_{F} - i_{F})\Delta_{n}\beta\alpha_{n}^{-2}K_{n}}, \frac{|S_{F}^{3} \cap \widetilde{F}|}{d_{\max}|S_{F}^{3} \cap \widetilde{F}|}\right\} \\ &\geq \min\left\{\frac{\eta'\alpha_{n}^{2}}{4d_{\max}\Delta_{n}K_{n}}, \frac{\alpha_{n}^{2}}{8d_{\max}\Delta_{n}\beta K_{n}}, \frac{1}{d_{\max}}\right\}, \end{aligned}$$

where the last inequality can be deduced by (4.17).

Combining (4.1), (4.16), (4.22) with Lemmas 3.1 and 4.1, our assertion holds.

By Cheeger's inequality (Proposition 6 in [16]), we have $\lambda_2 \leq 1 - \Phi^2$. Hence with probability 1, $\lambda_2 \leq 1 - \eta^2 r_n^2$ holds for large enough *n*. This completes the proof of our result.

5. Simulation example. In this section, we will provide a simulation example. Here, the number of agents is taken as n = 1000, and the interaction radius is $r_n = \sqrt{1.1 \log n/(\pi n)}$. The initial positions and headings of the *n* agents are independent, with positions uniformly and independently distributed in $[0, 1]^2$, and with headings uniformly and independently distributed in $(-\pi, \pi]$. Figure 4 shows how the probability of synchronization changes with moving speed. From this simulation, we see that if the speed is small, the system can synchronize w.h.p., and the probability of synchronization will tend to zero as the speed increases.



FIG. 4. Simulation results for the system with n = 1000, $r_n = \sqrt{1.1 \log n/(\pi n)}$, and the random initial states.

6. Concluding remarks. For the multiagent systems or flocks studied in this paper, it is intuitively obvious that the smaller the interaction radius is, the harder it is for the synchronization to happen. Thus, an important and interesting problem is how small the interaction radius can be in order to guarantee synchronization. This paper shows that in a certain sense, the smallest possible interaction radius for synchronization can be considered as the same as the critical radius for connectivity of the initial random geometric graph. We remark that an important step of this paper is to provide an estimation of the spectral gap of the average matrix of the random geometric graph. This result may be applied to other interesting problems, such as the mixing times and the hitting times of random walk on random geometric graphs.

REFERENCES

- [1] E. SHAW, Fish in schools, Natural History, 84 (1975), pp. 40-46.
- [2] J. K. PARRISH, S. V. VISCIDO, AND D. GRUNBAUM, Self-organized fish schools: An examination of emergent properties, Biol. Bull., 202 (2002), pp. 296–305.
- 3] T. VICSEK, A. CZIRÓK, E. BEN-JACOB, I. COHEN, AND O. SHOCHET, Novel type of phase transition in a system of self-driven particles, Phys. Rev. Lett., 75 (1995), pp. 1226–1229.

- [4] F. CUCKER AND S. SMALE, Emergent behavior in flocks, IEEE Trans. Automat. Control, 52 (2007), pp. 852–862.
- [5] C. REYNOLDS, Flocks, herds, and schools: A distributed behavioral model, Comput. Graphics, 21 (1987), pp. 25–34.
- [6] A. JADBABAIE, J. LIN, AND A. S. MORSE, Coordination of groups of mobile autonomous agents using nearest neighbor rules, IEEE Trans. Automat. Control, 48 (2003), pp. 988–1001.
- [7] A. V. SAVKIN, Coordinated collective motion of groups of autonomous mobile robots: Analysis of Vicsek's model, IEEE Trans. Automat. Control, 39 (2004), pp. 981–983.
- [8] G. G. TANG AND L. GUO, Convergence of a class of multi-agent systems in probabilistic framework, J. Syst. Sci. Complex., 20 (2007), pp. 173–197.
- W. REN AND R. W. BEARD, Consensus seeking in multiagent systems under dynamically changing interaction topologies, IEEE Trans. Automat. Control, 50 (2005), pp. 655–661.
- [10] Z. X. LIU AND L. GUO, Synchronization of multi-agent systems without connectivity assumption, Automatica, 45 (2009), pp. 2744–2753.
- R. OLFATI-SABER, Flocking for multi-agent dynamic systems: Algorithms and theory, IEEE Trans. Automat. Control, 51 (2006), pp. 401–420.
- [12] G. G. TANG AND L. GUO, Convergence analysis of linearized Vicseks model, in Proceedings of the 25th Chinese Control Conference, Harbin, China, 2006, pp. 379–382.
- [13] P. GUPTA AND P. R. KUMAR, Critical power for asymptotic connectivity in wireless networks, in Stochastic Analysis, Control, Optimization and Applications, Birkhäuser Boston, Boston, MA, 1999, pp. 547–566.
- [14] P. GUPTA AND P. R. KUMAR, The capacity of wireless networks, IEEE Trans. Inform. Theory, 46 (2000), pp. 388–404.
- [15] M. D. PENROSE, Random Geometric Graphs, Oxford University Press, Oxford, UK, 2003.
- [16] P. DIACONIS AND D. STROOK, Geometric bounds for eigenvalues of Markov chains, Ann. Appl. Probab., 1 (1991), pp. 36–61.
- [17] L. SALOFF-COSTE AND J. ZÚÑIGA, Merging for time inhomogeneous finite Markov chains, Part I: Singular values and stability, Electron. J. Probab., 14 (2009), pp. 1456–1494.
- [18] P. MATHIEU AND E. REMY, Isoperimetry and heat kernel decay on percolation clusters, Ann. Probab., 32 (2004), pp. 100–128.
- [19] G. GRIMMETT, Percolation, 2nd ed., Springer, Berlin, 1999.
- [20] M. D. PENROSE AND A. PISZTORA, Large deviations for discrete and continuous percolation, Adv. Appl. Probab., 28 (1996), pp. 29–52.

1970